

## Buoyancy and stability

The vertical mom. eqn. is written as:

$$\frac{Dw}{Dt} = -\frac{1}{\rho} \frac{\partial P}{\partial z} - g \quad (1)$$

We know hydrostatic balances is the leading-order balance in the atmosphere. Acceleration is small

$$\frac{Dw}{Dt} \ll g$$

To elucidate the acceleration, we separate  $P$  and  $g$  into hydrostatic and perturbation components.

$$P = P_0 + P' \quad g = g_0 + g' \quad g_0 \gg P' \\ \begin{matrix} \text{hydrostatic} \\ \text{perturbation} \end{matrix} \quad \begin{matrix} g_0 \gg P' \\ P_0 \gg P' \end{matrix}$$

We state that  $\frac{1}{\rho_0} \frac{\partial P_0}{\partial z} \equiv g \quad (2)$

exact by definition

Expand  $g$  and  $P$  in Eq. (1)

$$\frac{Dw}{Dt} = \frac{-1}{\rho_0 + g'} \frac{\partial}{\partial z} (P_0 + P') - g$$

$$\frac{1}{\rho_0} \left( \frac{1}{1 + g'/\rho_0} \right) \underset{\substack{\text{Expand into} \\ \text{Taylor Series}}}{\approx} \frac{1}{\rho_0} \left( 1 - \frac{g'}{\rho_0} \right) = \frac{1}{\rho_0} - \frac{g'}{\rho_0^2}$$

$$\begin{aligned} \frac{Dw}{Dt} &= -\left( \frac{1}{\rho_0} - \frac{g'}{\rho_0^2} \right) \left( \frac{\partial P_0}{\partial z} + \frac{\partial P'}{\partial z} \right) - g \\ &= -\left[ \cancel{\frac{1}{\rho_0} \frac{\partial P_0}{\partial z}} - \frac{g'}{\rho_0^2} \frac{\partial P_0}{\partial z} + \frac{1}{\rho_0} \frac{\partial P'}{\partial z} - \cancel{\frac{g'}{\rho_0^2} \frac{\partial P'}{\partial z}} \right] - g \end{aligned}$$

Smaller than the rest

cancel out b.c. of Eq. (2)

$$\begin{aligned} \frac{Dw}{Dt} &= \frac{g'}{\rho_0^2} \frac{\partial P_0}{\partial z} - \frac{1}{\rho_0} \frac{\partial P'}{\partial z} \\ &= -\frac{g'}{\rho_0} g - \frac{1}{\rho_0} \frac{\partial P'}{\partial z} \\ &\quad \text{Buoyancy} \end{aligned}$$